Computing minimal mappings

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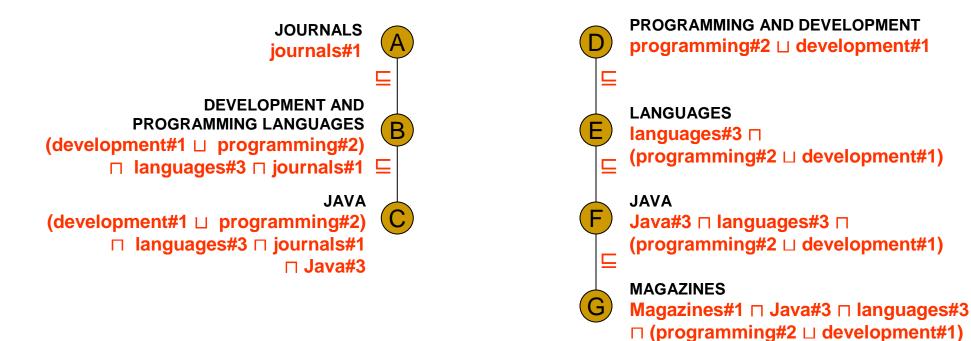


Roadmap

- Lightweight ontologies
- Mapping and minimal mapping
 - Computing a mapping: SMatch
 - Computing the minimal mapping: MinSMatch
- Evaluation
- Conclusions

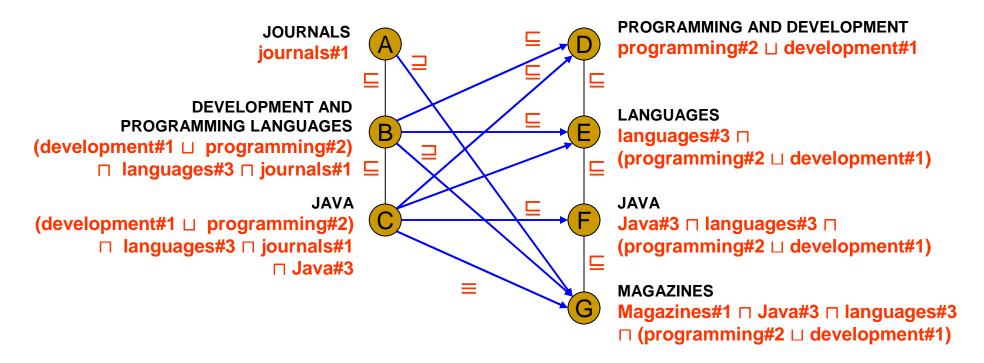
Lightweight ontologies (formal classifications)

- We translate the graphs in input into lightweight ontologies
 - Node labels are formulas in propositional Description Logic (DL)
 - Concepts are taken from WordNet senses
 - Tree structures: each node formula is subsumed by parent node formula



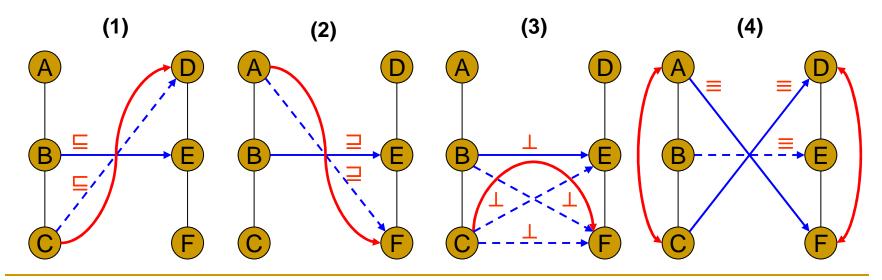
Computing a mapping using SMatch

- A Mapping is a set of mapping elements < source, target, R >
 - □ $R \in \{ '\bot', '\equiv', '\sqsubseteq', '\supseteq' \}$ partially ordered
 - For each pair of nodes a call to a SAT solver verifies if a given semantic relation holds between the two, given the available <u>background knowledge</u>
 - Visualization and usability problems (e.g. validation and maintenance)



Redundancy patterns

- We provide:
 - A definition of redundant mapping element (dashed arrows) based on the redundancy patterns below (redundancy w.r.t. another element).
 - A demonstration of soundness and completeness
- Dependencies across-symbols: equivalence is the combination of more and less specific
 - Pattern 4 can be seen as the combination of patterns 1 and 2
 - Patterns 1 and 2 are still valid in case of equivalence between B-E

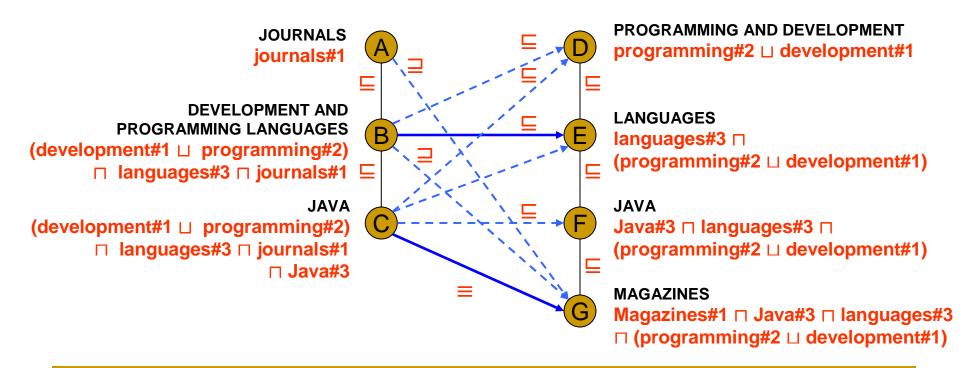


Minimal and redundant mappings

- We compute the Minimal Mapping
 - The subset of mapping elements of maximum size among those without redundant elements
- A Redundant Mapping
 - is a set containing redundant mapping elements
- The Mapping of maximum size
 - is the set containing the maximum number of mapping elements
 - It can be obtained from the propagation of the elements in the minimal set.

MinSMatch: computing the minimal mapping

- The minimal mapping always exists and it is unique
- Advantages in visualization, validation and maintenance



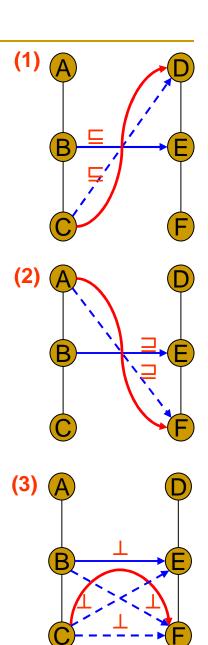
MinSMatch: the algorithm

Computing the minimal mapping M:

```
function TreeMatch(tree T1, tree T2) {
    TreeDisjoint(root(T1),root(T2)); (3)
    direction := true;
    TreeSubsumedBy(root(T1),root(T2)); (1)
    direction := false;
    TreeSubsumedBy(root(T2),root(T1)); (2)
    TreeEquiv(); (4) from (1) and (2)
};
```

Computing the set of maximum size:

function Propagate(M)



MinSMatch: evaluation w.r.t. SMatch

We evaluated it on 4 datasets of different dimensions:

```
□ 34 x 39 (University courses)
```

- □ 542 x 999 (Art domain)
- □ 2857 x 6628 (Web directories)
- □ 3358 x 5239 (Business directories)
- SAT calls: 43-66% less
- Runtime: 16-59% less
- Size of the minimal mapping: 68-96% less
- Recall: up to 0.6% elements more (*)
- (*) We minimize the problem of lack of background knowledge; the deeper the classifications the better.
 - The result of the propagation of the minimal set computed by MinSMatch is equivalent to the result of SMatch modulo inconsistencies.

Conclusions

The minimal mapping:

- always exists and it is unique
- offers usability advantages in visualization, validation and maintenance

The MinSMatch algorithm:

- significantly faster w.r.t. SMatch
- efficiently computes the mapping of maximum size (by propagation)
- increased recall (the deeper the classifications the better)

Next steps:

- Experimenting MinSmatch on large scale knowledge organization systems (>400k nodes)
- Avoid SAT
- User interaction issues (navigation and validation tasks)

Questions



Search on google and Wikipedia: Minimal mappings

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